

Torque motor data for ERD12 for not Schunk supported controller

Type of motor: ERD12

Date of creation: 06.03.2023

Description	Symbol	Unit	Value
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Data

Nominal motor torque	F_{nenn} [1]	Nm	1,2
Motor peak torque	$F_{max.}$ [1]	Nm	3,6
Motor idle current (eff.)	I_{nenn} [1,2]	A eff	1,1
Motor peak current (eff.)	$I_{max.}$ [1,2]	A eff	3,27
max. motor speed	$n_{max.}$	U/min	600
Power loss	P [1]	W	18,4
Torque / Force constant	k_{Kraft}	Nm/A	1,1
Motor constant	k_{Motor}	Nm/ $\sqrt{W}$	0,3
BEMF (speed 600 U/min)	k_{EMK}	Vss	116
Thermal time constant	$k_{therm.}$	s	1200
Resistance	$R_{(Phase\ Phase)}$	Ohm	13,7
Inductance	$L_{(Phase\ Phase)}$	mH	13,8
Number of pol pairs			7
Mass of motor	m	kg	1,9
Nominal intermediate circuit voltage	U_{nom} [2]	V	530
Max. intermediate circuit voltage	$U_{max.}$ [2]	V	900
Max. coil temperature	$T_{max.}$	°C	90
Type of temperature sensor			PTC

Control parameters

Current loop propotional gain		V/A	13
Current loop integral action time		ms	0,5
Position loop KV-Factor	k_v	1000/min	1
Velocity loop smoothing time const.		us	500
Velocity loop propotional gain	k_p	N/(mm/min)	0,03
Velocity loop integral action time	T_N	ms	10

Encoder Feedback

Motor	ERS	MRDS	ERD	ERI
Sensor designation	LE100	Encoder Kit R	SKM36	SKS90
Manufactor	SIKO	Numerik	Sick	Sick
Supply voltage	5 V	5V	7-12V	7-12V
Waveform	sin/cos	sin/cos	sin/cos / Hiperface	sin/cos / Hiperface
Reference mark	1	1	--	--
Signal amplitude	1 Vss	1 Vss	1 Vss	1Vss
Feedback revolution	160	2048	128	64

Motor connection

Connector	Connector	Contact
Interconnectron Typ: LEAB08AN	U	thick 1
	V	thick 4
	W	thick 3
PTC	GND	thick 2
		thin C
	PTC	thin D

Motor feedback

	ERS	MRDS	ERD	ERI
	Sub D pin	Sub D pin	Sub D pin	Sub D pin
Signal	Pin	Pin	Pin	Pin
0V Sense				
Ref - / EncData-	6	6	6	6
Ref + / EncData+	5	5	5	5
/B (COS-)	4	4	3	3
B(COS+)	3	3	4	4
A(SIN+)	1	1	2	2
/A(SIN-)	2	2	1	1
N.C.				
GND (0V)	7	7	7	7
N.C.				
Ucc	8	8	8	8
N.C.				
GND (Schirm)				
N.C.				